### Polytech Orléans – M1 AESM





# **Electrical Engineering**





### **Thomas TILLOCHER**

Université d'Orléans Laboratoire GREMI thomas.tillocher@univ-orleans.fr

Year 2025/2026





Original material: Emmanuel BEURUAY English version: Thomas TILLOCHER





### **Schedule**

	M1 AEMS
Lectures	14 x 1,25 h dont 2 DS
Tutorials	8 x 1,25 h
Lab work	1 x 2,50 h + 6 x 3,75 h

#### **Outline**

#### Introduction

- I) Reminders (electricity)
- II) Power in sinusoidal regime (single-phase and 3-phase)
- III) Transformers
- IV) Electric motors



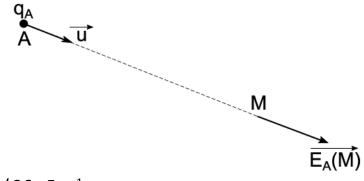
## **III - Transformers**

### **Reminders: electromagnetism**

- <u>The electrical field</u>: an electrical charge,  $q_A$ , placed at any point A in space, acts at any other point M in space, in the form of a vector field called the "electric field  $E_A(M)$ " expressed in V.m<sup>-1</sup>
- Electrical field due to charge q<sub>A</sub> at point M

$$\overrightarrow{E_A(M)} = \frac{q_A}{4.\pi. \varepsilon_0. AM^2}.\overrightarrow{u}$$

 $E_A(M)$  in V.m<sup>-1</sup>,  $q_A$  in C, AM in m  $\varepsilon_0$ , vacuum permittivity:  $\varepsilon_0 = 10^{-9} / 36\pi$  F.m<sup>-1</sup>



- Properties of the electrical field:
- => Inversely proportional to the square of the distance from its source. It scales with "1/r2"
- => Additive quantity





- The magnetic field: An electrical charge,  $q_A$ , located at any point A in space and moving with velocity "V", acts at any other point M in space, in the form of a vector field called the "magnetic field  $B_A(M)$ " expressed in Tesla (T).
- Magnetic field in vacuum at point M due to  $\text{charge displacement } \textbf{q}_{\textbf{A}}$

$$\overrightarrow{B_A(M)} = \frac{\mu_0}{4.\pi} \cdot \frac{q_A \cdot \overrightarrow{V} \wedge \overrightarrow{u}}{AM^2}$$

 $B_A(M)$  in Tesla,  $q_A$  in C, V in m/s, AM in m  $\mu_0$ , vacuum permeability in m.T.A.m<sup>-1</sup>,  $\mu_0$  = 4. $\pi$ .10<sup>-7</sup> m.T.A.m<sup>-1</sup> (or H.m<sup>-1</sup>)

#### - Properties of the magnetic field:

- => Inversely proportional to the square of the distance from its source. It varies in " $1/r^2$ ".
- => Additive quantity



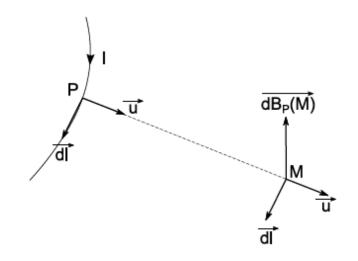


- The Biot and Savart's law: The elementary part dl of an electrical circuit in P through which a current of intensity I flows creates the "magnetic field  $dB_P(M)$ " at a point M in space

- Magnetic field at point M due to the current I flowing through the elementary part dl

$$\overrightarrow{dB_P(M)} = \frac{\mu_0}{4.\pi} \cdot \frac{I \cdot \overrightarrow{dl} \wedge \overrightarrow{PM}}{PM^3}$$

$$\overrightarrow{dB_P(M)} = \frac{\mu_0}{4.\pi} \cdot \frac{I \cdot \overrightarrow{dl} \wedge \overrightarrow{u}}{r^2}$$



- Total magnetic field in M created by the electrical circuit :  $\overrightarrow{B(M)} = \frac{\mu_0}{4.\,\pi}$  .  $\int\limits_{P \in circuit} \frac{I.\,dl \wedge u}{r^2}$ 



## **III - Transformers**

### **Reminders: electromagnetism**

- The excitation magnetic field  $\vec{H}$ : dHP(M), is related to the state of magnetic excitation of the medium and is given in A.m<sup>-1</sup>.
- Magnetic excitation field at point M due to the current I flowing through portion dl:

$$\overrightarrow{dH_P(M)} = \frac{1}{4.\pi} \cdot \frac{I \cdot \overrightarrow{dl} \wedge \overrightarrow{u}}{r^2}$$

- Total magnetic excitation field at M created by the wire through which a current I flows:

$$\overrightarrow{H(M)} = \frac{1}{4.\pi} \cdot \int_{P \in fil} \frac{I \cdot \overrightarrow{dl} \wedge \overrightarrow{u}}{r^2}$$

- If  $\vec{H}$  is the excitation magnetic field,  $\vec{B}$  is the magnetic induction field:  $\vec{B} = \mu_0 \mu_r \vec{H}$ 

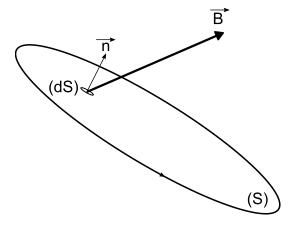
 $\mu_0$  vacuum permeability,  $\mu_r$  the relative permeability



- The magnetic flux: The flux of induction magnetic field B across a closed surface (S) is the quantity  $\phi_B$  given in Weber (Wb)

$$\Phi_B = \iint_{(S)} \overrightarrow{B}. \, \overrightarrow{n_{ext}}. \, dS$$

- The magnetic flux F is usually given by the product B.S
- If magnetic leakage is neglected, the flux in a magnetic circuit is conservative



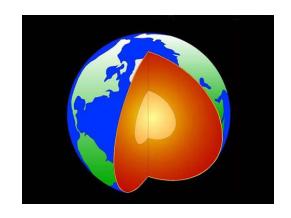
$$\Phi = B.S$$

Analogy with the garden hose :  $magnetic \ flux \ F \to flow$   $magnetic \ field \ B \to water \ speed$   $solenoid \ cross-section \ S \to pipe \ cross-section$ 





- Orders of magnitude
- Earth induction magnetic field: 50.10<sup>-6</sup> T



### In electrical machines:

- Induction magnetic field: 1 T à 1,5 T
- Excitation magnetic field: 1000 à 100000 A.m<sup>-1</sup>
- Magnetic flux: 10<sup>-5</sup> à 10<sup>-3</sup> Wb





## **III - Transformers**

### **Reminders: electromagnetism**

- <u>Ampere's theorem</u>: If (C) is a closed contour of space surrounding N wire conductors through which currents of intensities  $I_k$  flow, then the circulation of the magnetic excitation vector H along a closed contour I is equal to the sum of the entwined currents

$$\oint_{(C)} \vec{H} \cdot \vec{d\ell} = \sum_{k=1}^{k=N} i_k \qquad H \cdot \ell = N \cdot I$$

- Example:

$$\oint_{(C)} \overrightarrow{H} \cdot \overrightarrow{d\ell} = -i_1 + i_2 + i_3$$

- i<sub>1</sub> is counted as negative,
- i<sub>2</sub> and i<sub>3</sub> are counted as positive
- i<sub>4</sub> is outside the contour (not taken into account)





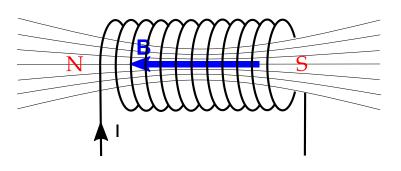


- Example: magnetic field created by a solenoid
- A solenoid is a straight winding with length I greater than its radius r.
- Inside the solenoid, far from its ends, the magnetic field is uniform.
- The field lines are parallel
- They enter at the coil's SOUTH face and exit at its NORTH face (corkscrew rule).

N: number of turns, I: length of solenoid

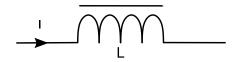
$$\overrightarrow{B} = \mu \times \overrightarrow{H}$$

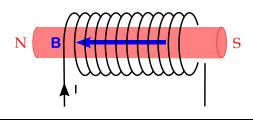
$$\mu = \mu_0 \times \mu_R$$



$$H = \frac{N.I}{l}$$

$$B=\mu_0.\frac{NI}{l}$$









### **Reminders: magnetic materials**

- Materials are classified according to their magnetic susceptibility  $\chi$
- =>  $\chi$  is related to the relative permeability through:  $\mu_r=1+\chi$
- Para-magnetic materials:  $\chi > 0$ , between  $10^{-3}$  and  $10^{-7}$
- => These materials are rare and their magnetization is negligible (Al, W, Pt, Sn...)
- dia-magnetic materials:  $\chi$  < 0, between 10<sup>-4</sup> and 10<sup>-6</sup>
- => These materials are common and their magnetization is negligible (non magnetic materials such as Cu, Bi, Au, Ag...)
- Ferro-magnetic materials:  $\chi > 0$ , between 10<sup>3</sup> and 10<sup>6</sup>
- => These are magnetic material of interest for magnetic circuits or transformer core (Fe, Ni, Co)





### **Reminders: magnetic materials**

- Magnetic materials are characterized by their hysteresis loop
  - => B=f(H) curve showing magnetizing/demagnetizing of the ferromagnetic material
- A ferromagnetic material that has never been magnetized will magnetize starting from O ("first magnetizing curve")
- The loop is run only in the direction of the arrows
- B<sub>S</sub>: saturation induction magnetic field
- B<sub>R</sub>: point of retentivity
- => Remanence of residual magnetism in the material
- H<sub>C</sub>: point of coercivity
- => Coercive excitation magnetic field required to remove the residual magnetism in the material

