

T5 – THE INDUCTION MACHINE

The aim of this tutorial is to study the induction machine using the equivalent model and the evolution of the mechanical torque-speed characteristic when the machine is supplied by a variable-frequency network.

The selected machine is an induction motor of brand “ABB” and type “M3AA 132 SMF 4”, whose main information is as follows:

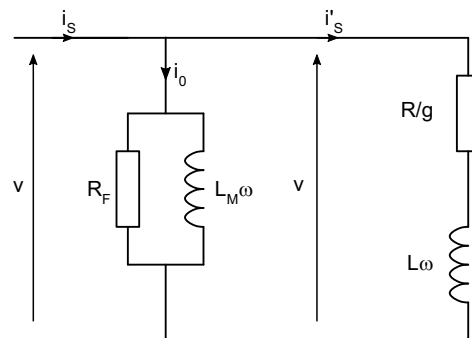
400V Y - 50Hz - 4 poles - 15kW

Study of the equivalent model of a machine stator winding

Equivalent model

The diagram shows the equivalent model of a machine stator winding.

- 1) **Remind** the meaning of the quantities R_F , $L_M \cdot \omega$, R and $L \cdot \omega$.



No-load test

The machine was tested at no load. The results of this test are as follows:

$U = 400V Y - f = 50Hz - I_0 = 14.70 A - P_0 = 420W$

- 2) **Remind** the rotational speed during this test and **calculate** the slip, g .
- 3) **Show** that the active and reactive powers, absorbed by the motor during this test, are absorbed only in the resistance R_F and the magnetizing reactance $L_M \cdot \omega$ respectively.
- 4) **Calculate** the power factor, the resistance R_F and the magnetizing reactance $L_M \cdot \omega$.

Blocked rotor test

The machine was tested with blocked rotor and reduced voltage. The results of this test were as follows:

$U_{RB} = 73,9V Y(\text{phase voltage}) - f = 50Hz - I_{RB} = 29,70 A - P_{RB} = 1330W$

- 5) **Remind** the rotational speed during this test and **calculate** the slip, g .
- 6) **Show** that the active and reactive powers, absorbed by the engine, are absorbed only in the resistance R/g and the reactance $X = L \cdot \omega$.

The machine is wye-connected. Measurement of the hot resistance between two terminals ($U1$ and $V1$) gave **0.319 0 Ω** .

- 7) **Calculate** the power factor, resistance R and reactance $X = L \cdot \omega$.

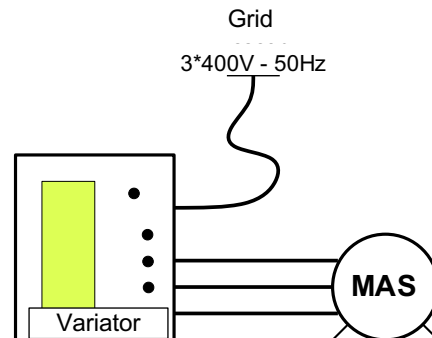
Exploiting the tests

- 8) **Show** that the electromagnetic torque, noted C_E , can be written: $C_E = 3 \cdot \frac{p}{\omega} \cdot \frac{V^2 \cdot R}{\frac{R^2}{g} + g \cdot (L \cdot \omega)^2}$
- 9) **Show** that the electromagnetic torque has a maximum, noted C_{EMax} , for the value noted g_{MAX} of the slip in motor operation. **Define** and **calculate** g_{MAX} and C_{EMax} .
- 10) From the torque expression, **calculate** C_{DEM} , the motor starting torque.
- 11) **Linearize** the torque characteristic in the useful part (sliding much less than g_{MAX}). **Then**, **express** C_E as a function of V , p , ω , R and g .

Association with a converter

A frequency converter is connected between the power grid and the induction machine. It modulates the frequency f of the stator currents while keeping the V/f ratio constant. In this section, the slip remains low with respect to g_{MAX} .

- 12) **Justify** the action of such a converter on the motor rotating speed n .



- 13) **Write** the torque as $C_E(n) = \alpha \cdot (\beta \cdot f - n)$. It is reminded that the V/f ratio is constant.
- 14) For $f = 50\text{Hz}$, $f = \frac{2}{3} \cdot 50\text{Hz}$ and $f = \frac{1}{3} \cdot 50\text{Hz}$, **plot** the characteristics $C_E(f;n)$ on the same graph.

The motor drives a machining system whose resistant torque is:

$$C_R = 0,04 \cdot n + 40$$

C_{RES} in N.m,
 n in rpm.

- 15) **Calculate** the coordinates of the operating points for each of the three frequencies.
- 16) **Decompose**, through a simple diagram, a frequency inverter and **represent** the shape of the characteristic voltages in the variator.